



Existence and Hyers-Ulam stability of random impulsive stochastic functional integrodifferential equations with finite delays

Annamalai Anguraj, Kasinathan Ramkumar*, and Kasinathan Ravikumar

Department of Mathematics, PSG College of Arts and Science, Coimbatore, 641 014, India.

Abstract

In this article, we study the existence and Hyers-Ulam stability of random impulsive stochastic functional integrodifferential equations with finite delays. Firstly, we prove the existence of mild solutions to the equations by using Banach fixed point theorem. In the later case we explore the Hyers-Ulam stability results under the Lipschitz condition on a bounded and closed interval.

Keywords. Existence, Random impulsive, Hyers-Ulam stability, Integrodifferential equations.

2010 Mathematics Subject Classification. 35R12, 60H99, 35B40, 34G20.

1. INTRODUCTION

Stochastic differential equations (SDEs) captures the disturbance from random factors. By the interaction of stochastic process into mathematic models yields a better understanding of the corresponding real-world system [8]. Several systems are modelled using stochastic functional differential equations with impulses. In general, impulses appears at random time points, i.e., the impulse time and the impulsive function are random variables. Sanz-Serna et al. [11] investigated the ergodicity of dissipative differential equations subject to random impulses. The random impulsive differential equations with the existence, uniqueness and stability of solutions is studied (see [3, 5, 13, 14, 19] and the reference therein). Random impulsive stochastic differential equations are widely used in the fields of medicine, biology, economics, finance and so on. For example, the classical stock price model see [15]. However, the Hyers-Ulam stability problem of SDEs have not been used in many articles. Only few works have been reported in the Hyers-Ulam stability for SDEs, refer to [2, 9, 18].

To the best of our knowledge, there has not been much of a study relating to Ulam-Hyers stability for SDEs with random impulses has not been investigated. Motivated by the above studies, in this paper, we investigate the Hyers-Ulam stability for d-dimensional random impulsive stochastic functional integrodifferential equations of the form:

$$d[u(t)] = [\mathbf{f}(t, u_t) + \int_0^t \mathbf{P}(t, s, u_s) ds] dt + \mathbf{g}(t, u_t) dw(t), t \geq t_0, t \neq \zeta_k, \quad (1.1)$$

$$u(\zeta_k) = b_k(\tau_k)u(\zeta_k^-), k = 1, 2, \dots, \quad (1.2)$$

$$u_{t_0} = \zeta = \{\zeta(\theta) : -\tau \leq \theta \leq 0\}, \quad (1.3)$$

where τ_k is a random variable defined from Ω to $D_k \stackrel{def}{=} (0, d_k)$ for $k = 1, 2, \dots$, where $0 < d_k < +\infty$. Suppose that τ_i and τ_j are independent of each other as $i \neq j$ for $i, j = 1, 2, \dots$. Here, $\mathbf{f} : [t_0, T] \times \mathcal{C} \rightarrow \mathbb{R}^d$, $\mathbf{g} : [t_0, T] \times \mathcal{C} \rightarrow \mathbb{R}^{d \times m}$,

Received: 18 March 2019 ; Accepted: 12 December 2020.

* Corresponding author. Email: ramkumarkpsg@gmail.com.

$\mathbf{P} : [t_0, T] \times [t_0, T] \times \mathcal{C} \rightarrow \mathbf{R}^d$ and $b_k : \mathbf{D}_k \rightarrow \mathbf{R}^{d \times d}$ are Borel measurable functions, and u_t is \mathbf{R}^d -valued stochastic process such that

$$u_t = \{u(t+\theta) : -\tau \leq \theta \leq 0\}, \quad u_t \in \mathbf{R}^d.$$

The impulsive moments ζ_k from a strictly increasing sequence, i.e. $\zeta_0 < \zeta_1 < \zeta_2 < \dots < \zeta_k < \dots < \lim_{k \rightarrow \infty} \zeta_k = \infty$, and $u(\zeta_k^-) = \lim_{t \rightarrow \zeta_k^-} u(t)$. We assume that $\zeta_0 = t_0$ and $\zeta_k = \zeta_{k-1} + \tau_k$ for $k = 1, 2, \dots$. Obviously, $\{\zeta_k\}$ is a process with independent increments. We suppose that $\{\mathbf{N}(t), t \geq 0\}$ is the simple counting process generated by $\{\zeta_k\}$, and $\{\mathcal{W}(t), t \geq 0\}$ is a given m -dimensional Wiener process. We denote $\mathcal{F}_t^{(1)}$ the σ -algebra generated by $\{\mathbf{N}(t), t \geq 0\}$, and denote $\mathcal{F}_t^{(2)}$ the σ -algebra generated by $\{\mathcal{W}(s), s \leq t\}$.

2. PRELIMINARIES

Let $(\Omega, \mathcal{F}, \mathbf{P})$ is a probability space with filtration $\{\mathcal{F}_t\}$, $t \geq 0$ satisfying $\mathcal{F}_t = \mathcal{F}_t^{(1)} \vee \mathcal{F}_t^{(2)}$. Let $\mathcal{L}^p(\Omega, \mathbf{R}^d)$ be the collection of all strongly measurable, p -th integrable, \mathcal{F}_t measurable, \mathbf{R}^d -valued random variables x with norm $\|u\|_{\mathcal{L}^p} = (\mathbf{E} \|u\|^p)^{\frac{1}{p}}$, Let $\tau > 0$ and denote the Banach space of all piecewise continuous \mathbf{R}^d -valued stochastic process $\{\zeta(t), t \in [-\tau, 0]\}$ by $\mathcal{C}([-\tau, 0], \mathcal{L}(\Omega, \mathbf{R}^d))$ equipped with the norm

$$\|\psi\|_{\mathcal{C}} = \sup_{\theta \in [-\tau, 0]} (\mathbf{E} \|\psi(\theta)\|^p)^{\frac{1}{p}}.$$

The initial data

$$u_{t_0} = \zeta = \{\zeta(\theta) : -\tau \leq \theta \leq 0\} \quad (2.1)$$

is an \mathcal{F}_{t_0} measurable, $[-\tau, 0]$ to \mathbf{R}^d -valued random variable such that $\mathbf{E} \|\zeta\|^p < \infty$.

Definition 2.1. For a given $T \in (t_0, +\infty)$, a \mathbf{R}^d -valued stochastic process $u(t)$ on $t_0 - \tau \leq t \leq T$ is called a solution to (1.1)-(1.3) with the initial data (2.1) if for every $t_0 \leq t \leq T$, $u_{t_0} = \zeta$, $\{u_t\}_{t_0 \leq t \leq T}$ is \mathcal{F}_t -adapted and

$$\begin{aligned} u(t) = & \sum_{k=0}^{+\infty} \left[\prod_{i=1}^k b_i(\tau_i) \zeta(0) + \sum_{i=1}^k \prod_{j=i}^k b_j(\tau_j) \int_{\zeta_{i-1}}^{\zeta_i} \mathbf{f}(s, u_s) ds + \int_{\zeta_k}^t \mathbf{f}(s, u_s) ds \right. \\ & + \sum_{i=1}^k \prod_{j=i}^k b_j(\tau_j) \int_{\zeta_{i-1}}^{\zeta_i} \int_0^s \mathbf{P}(s, r, u_r) dr ds + \int_{\zeta_k}^t \int_0^s \mathbf{P}(s, r, u_r) dr ds \\ & \left. + \sum_{i=1}^k \prod_{j=i}^k b_j(\tau_j) \int_{\zeta_{i-1}}^{\zeta_i} \mathbf{g}(s, u_s) dw(s) + \int_{\zeta_k}^t \mathbf{g}(s, u_s) dw(s) \right] I_{(\zeta_k, \zeta_{k-1}]}(t) \text{ a.s.} \end{aligned} \quad (2.2)$$

where $\prod_{j=i}^k b_j(\tau_j) = b_k(\tau_k) b_{k-1}(\tau_{k-1}) \dots b_i(\tau_i)$, and $I_{\mathbf{G}}(\cdot)$ is the index function, i.e.

$$I_{\mathbf{G}}(t) = \begin{cases} 1, & \text{if } t \in \mathbf{G}, \\ 0, & \text{if } t \notin \mathbf{G}. \end{cases}$$

Definition 2.2. Hyers-Ulam stability: Suppose that $v(t)$ is a \mathbf{R}^d -valued stochastic process. If there exists a real number $M > 0$, such that for arbitrary $\epsilon \geq 0$, satisfying

$$\begin{aligned} \mathbf{E} \left\| v(t) - \sum_{k=0}^{+\infty} \left[\prod_{i=1}^k b_i(\tau_i) \zeta(0) + \sum_{i=1}^k \prod_{j=i}^k b_j(\tau_j) \int_{\zeta_{i-1}}^{\zeta_i} \mathbf{f}(s, v_s) ds + \int_{\zeta_k}^t \mathbf{f}(s, v_s) ds \right. \right. \\ \left. + \sum_{i=1}^k \prod_{j=i}^k b_j(\tau_j) \int_{\zeta_{i-1}}^{\zeta_i} \int_0^s \mathbf{P}(s, r, v_r) dr ds + \int_{\zeta_k}^t \int_0^s \mathbf{P}(s, r, v_r) dr ds \right. \\ \left. \left. + \sum_{i=1}^k \prod_{j=i}^k b_j(\tau_j) \int_{\zeta_{i-1}}^{\zeta_i} \mathbf{g}(s, v_s) dw(s) + \int_{\zeta_k}^t \mathbf{g}(s, v_s) dw(s) \right] I_{(\zeta_k, \zeta_{k-1}]}(t) \right\|^p \leq \epsilon. \end{aligned}$$



For each solution $u(t)$ with the initial value $v_{t_0} = u_{t_0} = \zeta$, if there exists a solution $u(t)$ of equations (1.1)-(1.3) with

$$\mathbf{E} \|v(t) - u(t)\|^p \leq M\epsilon, \forall t \in (t_0 - \tau, T),$$

then equations (1.1)-(1.3) has the Hyers-Ulam stability.

Lemma 2.3. [3] Let $\phi, \varphi \in \mathcal{C}([a, b], \mathbf{R}^d)$ be two functions. We suppose that $\phi(t)$ is nondecreasing. If $u(t) \in \mathcal{C}([a, b], \mathbf{R}^d)$ is a solution of the following inequality

$$u(t) \leq \phi(t) + \int_a^t \varphi(s)u(s)ds, \quad t \in [a, b],$$

then $u(t) \leq \phi(t) \exp(\int_a^t \varphi(s)ds)$.

Lemma 2.4. [8] For any $p \geq 1$ and for any predictable process $u \in \mathcal{L}_{d \times m}^p[0, T]$, the inequality holds,

$$\sup_{s \in [0, t]} \mathbf{E} \|u(t)dw(t)\|^p \leq (p/2(p-1))^{p/2} \left(\int_0^t (\mathbf{E} \|u(s)\|^p)^{2/p} ds \right)^{p/2}, \quad t \in [0, T].$$

3. MAIN RESULTS

Here, we will consider the existence results for system (1.1)-(1.3). Now we introduce the following hypotheses used in our discussion:

(H1) The function $\mathbf{f} : [t_0, T] \times \mathcal{C} \rightarrow \mathbf{R}^d$ satisfies the following conditions: there exist positive constant $L_1, L_2 > 0$ such that, for all $t \in [t_0, T]$ and $\psi_1, \psi_2 \in \mathcal{C}$

$$\begin{aligned} \mathbf{E} \|\mathbf{f}(t, \psi_1) - \mathbf{f}(t, \psi_2)\|^p &\leq L_1 \|\psi_1 - \psi_2\|_{\mathcal{C}}^p, \\ \mathbf{E} \|\mathbf{f}(t, \psi)\|^p &\leq L_2 (1 + \|\psi\|_{\mathcal{C}}^p). \end{aligned}$$

(H2) For the continuous function $\mathbf{g} \in \mathcal{L}^p([t_0, T] \times \mathcal{C} : \mathbf{R}^{d \times m})$, there exists a constant $L_3, L_4 > 0$ such that, for all $t \in [t_0, T]$ and $\psi_1, \psi_2 \in \mathcal{C}$

$$\begin{aligned} \mathbf{E} \|\mathbf{g}(t, \psi_1) - \mathbf{g}(t, \psi_2)\|^p &\leq L_3 \|\psi_1 - \psi_2\|_{\mathcal{C}}^p, \\ \mathbf{E} \|\mathbf{g}(t, \psi)\|^p &\leq L_4 (1 + \|\psi\|_{\mathcal{C}}^p). \end{aligned}$$

(H3) The function $\mathbf{P} : [t_0, T] \times [t_0, T] \times \mathcal{C} \rightarrow \mathbf{R}^d$, there exists a constant $L_5, L_6 > 0$ such that, for all $t \in [t_0, T]$ and $\psi_1, \psi_2 \in \mathcal{C}$

$$\begin{aligned} \int_0^t \mathbf{E} \|\mathbf{P}(t, s, \psi_1) - \mathbf{P}(t, s, \psi_2)\|^p &\leq L_5 \|\psi_1 - \psi_2\|_{\mathcal{C}}^p, \\ \int_0^t \mathbf{E} \|\mathbf{P}(t, s, \psi)\|^p &\leq L_6 (1 + \|\psi\|_{\mathcal{C}}^p). \end{aligned}$$

(H4) The condition $\mathbf{E} \left\{ \max_{i,k} \left\{ \prod_{j=i}^k \|b_j(\tau_j)\|^p \right\} \right\} < \infty$. That is, there is a constant $B > 0$ such that

$$\mathbf{E} \left(\max_{i,k} \left\{ \prod_{j=i}^k \|b_j(\tau_j)\| \right\} \right)^p \leq B.$$

Theorem 3.1. Suppose that the assumptions (H1)-(H4) are satisfied. Then the system (1.1)-(1.3) has a unique solution in \mathcal{B} .

Proof. Let \mathcal{B} be the space $\mathcal{B} = \mathcal{C}([t_0 - \tau, T], \mathcal{L}^p(\Omega, \mathbf{R}^d))$ endowed using the norm

$$\|u\|_{\mathcal{B}}^p = \sup_{t \in [t_0, T]} \|u_t\|_{\mathcal{C}}^p,$$



where $\|u_t\|_{\mathcal{E}} = \sup_{-\tau \leq s \leq t} \mathbf{E} \|u(s)\|^p$. Denote $\mathbf{B}_r = \{u \in \mathcal{B}; \|u\|_{\mathcal{B}}^p \leq r\}$, which is the closed ball with center u and radius $r > 0$. For any initial value (t_0, u_0) $t_0 \geq 0$ and $u_0 \in \mathbf{B}_r$.

we define the operator $\Theta : \mathcal{B} \rightarrow \mathcal{B}$ by

$$\begin{aligned} (\Theta u)(t) &= \sum_{k=0}^{+\infty} \left[\prod_{i=1}^k b_i(\tau_i) \zeta(0) + \sum_{i=1}^k \prod_{j=i}^k b_j(\tau_j) \int_{\zeta_{i-1}}^{\zeta_i} \mathbf{f}(s, u_s) ds + \int_{\zeta_k}^t \mathbf{f}(s, u_s) ds \right. \\ &\quad + \sum_{i=1}^k \prod_{j=i}^k b_j(\tau_j) \int_{\zeta_{i-1}}^{\zeta_i} \int_0^s \mathbf{P}(s, r, u_r) dr ds + \int_{\zeta_k}^t \int_0^s \mathbf{P}(s, r, u_r) dr ds \\ &\quad \left. + \sum_{i=1}^k \prod_{j=i}^k b_j(\tau_j) \int_{\zeta_{i-1}}^{\zeta_i} \mathbf{g}(s, u_s) dw(s) + \int_{\zeta_k}^t \mathbf{g}(s, u_s) dw(s) \right] I_{(\zeta_k, \zeta_{k+1}]}(t). \end{aligned}$$

The continuity of Θ can be proved easily. Now, we claim that Θ maps \mathcal{B} into itself.

$$\begin{aligned} \mathbf{E} \|(\Theta u)(t)\|^p &\leq 4^{p-1} \max_k \mathbf{E} \left\{ \prod_{i=1}^k \|b_i(\tau_i)\|^p \right\} \|u_0\|^p + 4^{p-1} \mathbf{E} \left[\max_{i,k} \left\{ 1, \prod_{j=i}^k \|b_j(\tau_j)\| \right\} \right]^p \left[\int_{t_0}^t \|\mathbf{f}(s, u_s)\| ds I_{(\zeta_k, \zeta_{k+1}]}(t) \right]^p \\ &\quad + 4^{p-1} \mathbf{E} \left[\max_{i,k} \left\{ 1, \prod_{j=i}^k \|b_j(\tau_j)\| \right\} \right]^p \left[\int_{t_0}^t \int_0^s \|\mathbf{P}(s, r, u_r)\| dr ds I_{(\zeta_k, \zeta_{k+1}]}(t) \right]^p \\ &\quad + 4^{p-1} \mathbf{E} \left[\max_{i,k} \left\{ 1, \prod_{j=i}^k \|b_j(\tau_j)\| \right\} \right]^p \left[\int_{t_0}^t \|\mathbf{g}(s, u_s)\| dw(s) I_{(\zeta_k, \zeta_{k+1}]}(t) \right]^p \\ &\leq 4^{p-1} \mathbf{B} \mathbf{E} \|x_0\|^p + 4^{p-1} \max(1, \mathbf{B})(t - t_0)^{p-1} L_2 \int_{t_0}^t \mathbf{E}(1 + \|u_s\|_{\mathcal{E}}^p) ds \\ &\quad + 4^{p-1} \max(1, \mathbf{B})(t - t_0)^{p-1} L_6 \int_{t_0}^t \mathbf{E}(1 + \|u_s\|_{\mathcal{E}}^p) ds + 4^{p-1} \max(1, \mathbf{B})(t - t_0)^{\frac{p}{2}-1} c_p L_4 \int_{t_0}^t \mathbf{E}(1 + \|u_s\|_{\mathcal{E}}^p) ds. \end{aligned}$$

Thus

$$\begin{aligned} \sup_{s \in [t-\tau, t]} \mathbf{E} \|(\Theta u)(t)\|^p &\leq 4^{p-1} \mathbf{B} \mathbf{E} \|u_0\|^p + [4^{p-1} \max(1, \mathbf{B})(t - t_0)^{p-1} L_2 \\ &\quad + 4^{p-1} \max(1, \mathbf{B})(t - t_0)^{\frac{p}{2}-1} c_p L_4 + 4^{p-1} \max(1, \mathbf{B})(t - t_0)^{p-1} L_6] (t - t_0) \sup_{s \in [t-\tau, t]} \mathbf{E}(1 + \|u_s\|_{\mathcal{E}}^p). \end{aligned}$$

Therefore Θ maps \mathcal{B} into itself.

Now, we have to prove that Θ is a contraction mapping

$$\begin{aligned} \mathbf{E} \|(\Theta u)(t) - (\Theta v)(t)\|^p &\leq 3^{p-1} \mathbf{E} \left[\max_{i,k} \left\{ 1, \prod_{j=i}^k \|b_j(\tau_j)\| \right\} \right]^p \left[\int_{t_0}^t \mathbf{E} \|\mathbf{f}(s, u_s) - \mathbf{f}(s, v_s)\| ds \right]^p \\ &\quad + 3^{p-1} \mathbf{E} \left[\max_{i,k} \left\{ 1, \prod_{j=i}^k \|b_j(\tau_j)\| \right\} \right]^p \left[\int_{t_0}^t \int_0^s \mathbf{E} \|\mathbf{P}(s, r, u_r) - \mathbf{P}(s, r, v_r)\| dr ds \right]^p \\ &\quad + 3^{p-1} \mathbf{E} \left[\max_{i,k} \left\{ 1, \prod_{j=i}^k \|b_j(\tau_j)\| \right\} \right]^p \left[\int_{t_0}^t \mathbf{E} \|\mathbf{g}(s, u_s) - \mathbf{g}(s, v_s)\| dw(s) \right]^p \\ &\leq 3^{p-1} \max\{1, \mathbf{B}\} (t - t_0)^p L_1 \|u_s - v_s\|_{\mathcal{E}}^p + 3^{p-1} \max\{1, \mathbf{B}\} (t - t_0)^p L_5 \|u_s - v_s\|_{\mathcal{E}}^p \\ &\quad + 3^{p-1} \max\{1, \mathbf{B}\} c_p (t - t_0)^{\frac{p}{2}} L_3 \|u_s - v_s\|_{\mathcal{E}}^p \\ &\leq 3^{p-1} \max_{1, \mathbf{B}} [L_1(t - t_0)^p + L_5(t - t_0)^p + c_p L_3(t - t_0)^{\frac{p}{2}}] \sup_{\theta \in [t-\tau, 0]} \mathbf{E} \|u(t + \theta) - v(t + \theta)\|^p \\ &\leq 3^{p-1} \max_{1, \mathbf{B}} [L_1(t - t_0)^p + L_5(t - t_0)^p + c_p L_3(t - t_0)^{\frac{p}{2}}] \sup_{s \in [t-\tau, t]} \mathbf{E} \|u(s) - v(s)\|^p. \end{aligned}$$



Taking the supremum over t , we obtain

$$\|(\Theta x)(t) - (\Theta y)(t)\|_{\mathcal{B}}^p \leq Q(T)\mathbf{E}\|u - v\|_{\mathcal{B}}^p,$$

where $Q(T) = 3^{p-1} \max_{1, \mathbf{B}} \left(L_1(t - t_0)^p + L_5(t - t_0)^p + c_p L_3(t - t_0)^{p/2} \right)$. By selecting a suitable $0 < T_1 < T$ sufficiently small enough such that $Q(T) < 1$, thus Θ is a contraction mapping. $\Theta u = u$ is a unique solution of equations (1.1)-(1.3) by Banach fixed point theorem. \square

4. STABILITY

Here, we will study the stability of the system (1.1)-(1.3) by the continuous dependence of solutions with initial condition.

Definition 4.1. A mild solution $u(t)$ of the system (1.1) and (1.2) with initial value ζ satisfies (2.2) is said to be stable in the mean square if for all $\epsilon > 0$, there exists $\delta > 0$ such that

$$\mathbf{E}\|u(t) - v(t)\|^p \leq \epsilon \text{ whenever } \mathbf{E}\|u - v\|^p < \delta, \text{ for all } t \in [t_0, T].$$

where $v(t)$ is another mild solution of the system (1.1) and (1.2) with initial value $\hat{\zeta}$ defined in (3).

Theorem 4.2. *The hypotheses of Theorem 3.1 are satisfied when the solution of the system (1.1)-(1.3) is stable in the mean square provided $u(t)$ and $v(t)$ being the mild solutions of the system (1.1)-(1.3) whose initial values being ζ_1 and ζ_2 .*

Proof. Let u and v be the two solutions of the system (1.1)-(1.3) with initial values ζ_1 and ζ_2 respectively, then

$$\begin{aligned} \mathbf{E}\|u(t) - v(t)\|^p &\leq 4^{p-1} \max_k \left\{ \prod_{i=1}^k \|b_i(\tau_i)\|^p \right\} \mathbf{E}\|\zeta_1 - \zeta_2\|^p \\ &\quad + 4^{p-1} \mathbf{E} \left[\max_{i,k} \left\{ 1, \prod_{j=i}^k \|b_j(\tau_j)\| \right\} \right]^p \left[\int_{t_0}^t \mathbf{E} \|\mathbf{f}(s, u_s) - \mathbf{f}(s, v_s)\| ds \right]^p \\ &\quad + 4^{p-1} \mathbf{E} \left[\max_{i,k} \left\{ 1, \prod_{j=i}^k \|b_j(\tau_j)\| \right\} \right]^p \left[\int_{t_0}^t \int_0^s \mathbf{E} \|\mathbf{P}(s, r, u_r) - \mathbf{P}(s, r, v_r)\| dr ds \right]^p \\ &\quad + 4^{p-1} \mathbf{E} \left[\max_{i,k} \left\{ 1, \prod_{j=i}^k \|b_j(\tau_j)\| \right\} \right]^p \left[\int_{t_0}^t \mathbf{E} \|\mathbf{g}(s, u_s) - \mathbf{g}(s, v_s)\| dw(s) \right]^p \\ &\leq 4^{p-1} \mathbf{B} \mathbf{E} \|\zeta_1 - \zeta_2\|^p + [4^{p-1} \max(1, \mathbf{B})(t - t_0)^{p-1} L_1 + 4^{p-1} \max(1, \mathbf{B})(t - t_0)^{p-1} L_5 \\ &\quad + 4^{p-1} \max(1, \mathbf{B}) c_p (t - t_0)^{\frac{p}{2}-1} L_3] \int_{t_0}^t \sup_{s \in [t-\tau, t]} \mathbf{E} \|u(s) - v(s)\|^p ds. \end{aligned}$$

Using Grownwall's inequality, we have

$$\begin{aligned} \sup_{s \in [t-\tau, t]} \mathbf{E} \|u(t) - v(t)\|^p &\leq 4^{p-1} \mathbf{B} \mathbf{E} \|\zeta_1 - \zeta_2\|^p \exp [4^{p-1} \max(1, \mathbf{B})(t - t_0)^{p-1} L_1 \\ &\quad + 4^{p-1} \max(1, \mathbf{B})(t - t_0)^{p-1} L_5 + 4^{p-1} \max(1, \mathbf{B}) c_p (t - t_0)^{\frac{p}{2}-1} L_3] \\ &\leq \Gamma \mathbf{E} \|\zeta_1 - \zeta_2\|^p, \end{aligned}$$

where

$$\Gamma = 4^{p-1} \mathbf{B} \exp [4^{p-1} \max(1, \mathbf{B})(t - t_0)^{p-1} L_1 + 4^{p-1} \max(1, \mathbf{B})(t - t_0)^{p-1} L_5 + 4^{p-1} \max(1, \mathbf{B}) c_p (t - t_0)^{\frac{p}{2}-1} L_3]$$

Given $\epsilon > 0$, determine $\delta = \frac{\epsilon}{\Gamma}$ such that $\mathbf{E} \|\zeta_1 - \zeta_2\|^p < \delta$. Then

$$\sup_{s \in [t-\tau, t]} \mathbf{E} \|u(t) - v(t)\|^p \leq \epsilon.$$



Which complete the proof. □

5. HYERS-ULAM STABILITY

Here, we will prove the Hyers-Ulam stability of Equation (1.1)-(1.3) with the assumptions (H1)-(H4).

Theorem 5.1. *If the hypotheses of Theorem 3.1 are satisfied, then Equation (1.1)-(1.3) has the Ulam-Hyers stability.*

Proof. We know that, $x(t)$ is the solution of equations (1.1)-(1.3).

$$\begin{aligned}
 u(t) = & \sum_{k=0}^{+\infty} \left[\prod_{i=1}^k b_i(\tau_i) \zeta(0) + \sum_{i=1}^k \prod_{j=i}^k b_j(\tau_j) \int_{\zeta_{i-1}}^{\zeta_i} \mathbf{f}(s, u_s) ds + \int_{\zeta_k}^t \mathbf{f}(s, u_s) \right. \\
 & + \sum_{i=1}^k \prod_{j=i}^k b_j(\tau_j) \int_{\zeta_{i-1}}^{\zeta_i} \int_0^s \mathbf{P}(s, r, u_r) dr ds + \int_{\zeta_k}^t \int_0^s \mathbf{P}(s, r, u_r) dr ds \\
 & \left. + \sum_{i=1}^k \prod_{j=i}^k b_j(\tau_j) \int_{\zeta_{i-1}}^{\zeta_i} \mathbf{g}(s, u_s) dw(s) + \int_{\zeta_k}^t \mathbf{g}(s, u_s) dw(s) \right] I_{(\zeta_k, \zeta_{k-1})}(t).
 \end{aligned}$$

It follows from the condition that

$$\begin{aligned}
 \mathbf{E} \left\| v(t) - \sum_{k=0}^{+\infty} \left[\prod_{i=1}^k b_i(\tau_i) \zeta(0) + \sum_{i=1}^k \prod_{j=i}^k b_j(\tau_j) \int_{\zeta_{i-1}}^{\zeta_i} \mathbf{f}(s, v_s) ds + \int_{\zeta_k}^t \mathbf{f}(s, v_s) ds \right. \right. \\
 + \sum_{i=1}^k \prod_{j=i}^k b_j(\tau_j) \int_{\zeta_{i-1}}^{\zeta_i} \int_0^s \mathbf{P}(s, r, v_r) dw(s) + \int_{\zeta_k}^t \int_0^s \mathbf{P}(s, r, v_r) dr ds \\
 \left. \left. + \sum_{i=1}^k \prod_{j=i}^k b_j(\tau_j) \int_{\zeta_{i-1}}^{\zeta_i} \mathbf{g}(s, v_s) dw(s) + \int_{\zeta_k}^t \mathbf{g}(s, v_s) dw(s) \right] \right\|^p \leq \epsilon.
 \end{aligned}$$

When $t \in [t_0 - \tau, t_0]$, we have, $\mathbf{E} \|v(t) - u(t)\|^p = 0$. And when $t \in [t_0, T]$, we have

$$\begin{aligned}
 \mathbf{E} \|v(t) - u(t)\|^p & \leq 2^{p-1} \mathbf{E} \left\| v(t) - \sum_{k=0}^{+\infty} \left[\prod_{i=1}^k b_i(\tau_i) \zeta(0) + \sum_{i=1}^k \prod_{j=i}^k b_j(\tau_j) \int_{\zeta_{i-1}}^{\zeta_i} \mathbf{f}(s, v_s) ds + \int_{\zeta_k}^t \mathbf{f}(s, v_s) ds \right. \right. \\
 & + \sum_{i=1}^k \prod_{j=i}^k b_j(\tau_j) \int_{\zeta_{i-1}}^{\zeta_i} \int_0^s \mathbf{P}(s, r, v_r) dr ds + \int_{\zeta_k}^t \int_0^s \mathbf{P}(s, r, v_r) dr ds \\
 & \left. \left. + \sum_{i=1}^k \prod_{j=i}^k b_j(\tau_j) \int_{\zeta_{i-1}}^{\zeta_i} \mathbf{g}(s, v_s) dw(s) + \int_{\zeta_k}^t \mathbf{g}(s, v_s) dw(s) \right] I_{(\zeta_k, \zeta_{k-1})}(t) \right\|^p \\
 & + 2^{p-1} \mathbf{E} \left\| \sum_{k=0}^{+\infty} \left[\sum_{i=1}^k \prod_{j=i}^k b_j(\tau_j) \int_{\zeta_{i-1}}^{\zeta_i} [\mathbf{f}(s, u_s) - \mathbf{f}(s, v_s)] ds + \int_{\zeta_k}^t [\mathbf{f}(s, u_s) - \mathbf{f}(s, v_s)] ds \right. \right. \\
 & + \sum_{i=1}^k \prod_{j=i}^k b_j(\tau_j) \int_{\zeta_{i-1}}^{\zeta_i} \int_0^s [\mathbf{P}(s, r, u_r) - \mathbf{P}(s, r, v_r)] dr ds + \int_{\zeta_k}^t \int_0^s [\mathbf{P}(s, r, u_r) - \mathbf{P}(s, r, v_r)] dr ds \\
 & \left. \left. + \sum_{i=1}^k \prod_{j=i}^k b_j(\tau_j) \int_{\zeta_{i-1}}^{\zeta_i} [\mathbf{g}(s, u_s) - \mathbf{g}(s, v_s)] dw(s) + \int_{\zeta_k}^t [\mathbf{g}(s, u_s) - \mathbf{g}(s, v_s)] dw(s) \right] I_{(\zeta_k, \zeta_{k-1})}(t) \right\|^p \\
 & \leq 2^{p-1} \epsilon + 2^{p-1} \mathfrak{G},
 \end{aligned}$$



where

$$\begin{aligned} \mathfrak{G} &= \mathbf{E} \left\| \sum_{k=0}^{+\infty} \left[\sum_{i=1}^k \prod_{j=i}^k b_j(\tau_j) \int_{\zeta_{i-1}}^{\zeta_i} [\mathbf{f}(s, u_s) - \mathbf{f}(s, v_s)] ds + \int_{\zeta_k}^t [\mathbf{f}(s, u_s) - \mathbf{f}(s, v_s)] ds \right. \right. \\ &\quad + \sum_{i=1}^k \prod_{j=i}^k b_j(\tau_j) \int_{\zeta_{i-1}}^{\zeta_i} \int_0^s [\mathbf{P}(s, r, u_r) - \mathbf{P}(s, r, v_r)] dr ds + \int_{\zeta_k}^t \int_0^s [\mathbf{P}(s, r, u_r) - \mathbf{P}(s, r, v_r)] dr ds \\ &\quad \left. \left. + \sum_{i=1}^k \prod_{j=i}^k b_j(\tau_j) \int_{\zeta_{i-1}}^{\zeta_i} [\mathbf{g}(s, u_s) - \mathbf{g}(s, v_s)] dw(s) + \int_{\zeta_k}^t [\mathbf{g}(s, u_s) - \mathbf{g}(s, v_s)] dw(s) \right] I_{(\zeta_k, \zeta_{k-1})}(t) \right\|^p \\ &\leq 3^{p-1} (\mathfrak{A} + \mathfrak{B} + \mathfrak{C}). \end{aligned}$$

First,

$$\begin{aligned} \mathfrak{A} &= \mathbf{E} \left\| \sum_{k=0}^{+\infty} \left[\sum_{i=1}^k \prod_{j=i}^k b_j(\tau_j) \int_{\zeta_{i-1}}^{\zeta_i} [\mathbf{f}(s, u_s) - \mathbf{f}(s, v_s)] ds + \int_{\zeta_k}^t [\mathbf{f}(s, u_s) - \mathbf{f}(s, v_s)] ds \right] I_{(\zeta_k, \zeta_{k-1})}(t) \right\|^p \\ &\leq (B^p + 1)(T - t_0)^{p-1} \int_{t_0}^t \mathbf{E} \|\mathbf{f}(s, u_s) - \mathbf{f}(s, v_s)\|^p ds \\ &\leq (B^p + 1)L_1(T - t_0)^{p-1} \int_{t_0}^t \|u_s - v_s\|^p ds. \end{aligned}$$

By (H3), we have

$$\begin{aligned} \mathfrak{B} &= \mathbf{E} \left\| \sum_{k=0}^{+\infty} \left[\sum_{i=1}^k \prod_{j=i}^k b_j(\tau_j) \int_{\zeta_{i-1}}^{\zeta_i} \int_0^s [\mathbf{P}(s, r, u_r) - \mathbf{P}(s, r, v_r)] ds + \int_{\zeta_k}^t \int_0^s [\mathbf{P}(s, r, u_r) - \mathbf{P}(s, r, v_r)] ds \right] I_{(\zeta_k, \zeta_{k-1})}(t) \right\|^p \\ &\leq (B^p + 1)(T - t_0)^{p-1} \int_{t_0}^t \mathbf{E} \|\mathbf{P}(s, r, u_r) - \mathbf{P}(s, r, v_r)\|^p ds \\ &\leq (B^p + 1)L_5(T - t_0)^{p-1} \int_{t_0}^t \|u_s - v_s\|^p ds. \end{aligned}$$

From Lemma 2.4 we have

$$\begin{aligned} \mathfrak{C} &= \mathbf{E} \left\| \sum_{k=0}^{+\infty} \left[\sum_{i=1}^k \prod_{j=i}^k b_j(\tau_j) \int_{\zeta_{i-1}}^{\zeta_i} [\mathbf{g}(s, u_s) - \mathbf{g}(s, v_s)] ds + \int_{\zeta_k}^t [\mathbf{g}(s, u_s) - \mathbf{g}(s, v_s)] ds \right] I_{(\zeta_k, \zeta_{k-1})}(t) \right\|^p \\ &\leq (B^p + 1)(p(p - 1))^{p/2} (T - t_0)^{(p-2)/2} \int_{t_0}^t \mathbf{E} \|\mathbf{g}(s, u_s) - \mathbf{g}(s, v_s)\|^p ds \\ &\leq (B^p + 1)L_3(p(p - 1)/2)^{p/2} (T - t_0)^{(p-2)/2} \int_{t_0}^t \|u_s - v_s\|^p ds. \end{aligned}$$

Therefore,

$$H \leq K \int_{t_0}^t \|u(s) - v(s)\|_{\mathcal{C}}^p ds,$$

where

$$K = 3^{p-1}(B^p + 1)(T - t_0)^{p/2-1} [L_1(T - t_0)^{p/2} + L_5(T - t_0)^{p/2} + (p(p - 1)/2)^{p/2} L_3].$$

Then, we obtain that

$$\mathbf{E} \|u(s) - v(s)\|^p \leq 2^{p-1}\epsilon + 2^{p-1}K \int_{t_0}^t \|v(s) - u(s)\|_{\mathcal{C}}^p ds.$$



Considering,

$$\begin{aligned} \int_{t_0}^t \|v(s) - u(s)\|_{\mathcal{E}}^p ds &= \int_{t_0}^t \sup_{\theta \in [-\tau, 0]} \mathbf{E} \|v(s + \theta) - u(s + \theta)\|^p ds \\ &= \sup_{\theta \in [-\tau, 0]} \int_{t_0}^t \mathbf{E} \|v(s + \theta) - u(s + \theta)\|^p ds \\ &= \sup_{\theta \in [-\tau, 0]} \int_{t_0 + \theta}^{t + \theta} \mathbf{E} \|v(l) - u(l)\|^p dl. \end{aligned}$$

Notice that, when $t \in [t_0 - \tau, t_0]$,

$$\mathbf{E} \|v(l) - u(l)\|^p = 0.$$

Therefore,

$$\int_{t_0}^t \|v_s - u_s\|_{\mathcal{E}}^p ds = \sup_{\theta \in [-\tau, 0]} \int_{t_0}^{t + \theta} \mathbf{E} \|v(l) - u(l)\|^p dl = \int_{t_0}^t \mathbf{E} \|v(l) - u(l)\|^p dl.$$

So, we get

$$\mathbf{E} \|v(t) - u(t)\|^p \leq 2^{p-1}\epsilon + 2^{p-1}K \int_{t_0}^t \mathbf{E} \|v(l) - u(l)\|^p dl.$$

From Lemma 2.3 we have

$$\mathbf{E} \|v(t) - u(t)\|^p \leq 2^{p-1}\epsilon \cdot \exp(2^{p-1}K).$$

Therefore, there exists $M = 2^{p-1} \cdot \exp(2^{p-1}K)$ such that

$$\mathbf{E} \|v(t) - u(t)\|^p \leq M\epsilon.$$

Thus the proof gets completed. □

6. CONCLUSION

This manuscript addresses the existence and Hyers-Ulam stability of random impulsive stochastic functional integrodifferential equations with finite delays. Firstly, we prove the existence of mild solutions to the equations by using Banach fixed point theorem. In the later case we explore the Hyers Ulam stability results under the Lipschitz condition on a bounded and closed interval. As further direction, researchers are invited to investigate the controllability of random impulsive stochastic functional integrodifferential equations with finite delays.

REFERENCES

- [1] A. Anguraj, A. Vinodkumar, and K. Malar, *Existence and stability results for random impulsive fractional pantograph equations*, *Filomat*, 30(14) (2016), 3839–3854.
- [2] A. Anguraj, K. Ravikumar, and J. J. Nieto, *On stability of stochastic differential equations with random impulses driven by Poisson jumps*, *Stochastics An International Journal of Probability and Stochastic Processes*, (2020), 1–15.
- [3] S. Dragomir, *Some Gronwall type inequalities and applications*, RGMIA Monographs, Nova Biomedical, Melbourne, (2002).
- [4] G. L. Forti, *Hyers-Ulam stability of functional equations in several variables*, *Aequationes Mathematicae*, 50(1-2) (1995), 143–190.
- [5] M. Gowrisankar, P. Mohankumar, and A. Vinodkumar, *Stability results of random impulsive semilinear differential equations*, *Acta Math. Sci*, 34(4) (2014), 1055–1071.
- [6] N. Lungu and D. Popa, *Hyers-Ulam stability of a first order partial differential equations*, *Journal of Mathematical Analysis and Applications*, 385 (2012), 86–91.



- [7] K. Malar, *Existence and uniqueness results for random impulsive integro-differential equation*, Global Journal of Pure and Applied Mathematics. *6* (2018), 809-817.
- [8] X. Mao, *Stochastic differential equations and applications*, M. Horwood, Chichester, (1997).
- [9] N. Ngoc, *Ulam-Hyers-Rassias stability of a nonlinear stochastic integral equation of Volterra type*, Differ. Equ. Appl, *9(2)* (2017), 183–193.
- [10] T. M. Rassias, *On the stability of fractional equations and a problem of Ulam*, Acta Appl. Math, *62(1)* (2000), 23–130.
- [11] J. M. Sanz-Serna and A. M. Stuart, *Ergodicity of dissipative differential equations subject to random impulses*, Journal of differential equations, *155(2)* (1999), 262–284.
- [12] R. Shah and A. Zada, *A fixed point approach to the stability of a nonlinear volterra integrodifferential equation with delay*, Hacet. J. Math. Stat, *47(3)* (2018), 615–623.
- [13] A. Vinodkumar, M. Gowrisankar, and P. Mohankumar, *Existence, uniqueness and stability of random impulsive neutral partial differential equations*, J. Egyptian Math. Soc, *23(1)* (2015), 31–36.
- [14] A. Vinodkumar, K. Malar, M. Gowrisankar, and P. Mohankumar, *Existence, uniqueness and stability of random impulsive fractional differential equations*, Acta Math. Sci, *36B(2)* (2016), 428–442.
- [15] T. Wang and S. Wu, *Random impulsive model for stock prices and its application for insurers*, Master thesis (in Chinese), Shanghai, East China Normal University, (2008).
- [16] S. Wu and X. Meng, *Boundedness of nonlinear differential systems with impulsive effect on random moments*, Acta Math. Appl. Sin, *20(1)* (2004), 147–154.
- [17] S. Wu and B. Zhou, *Existence and uniqueness of stochastic differential equations with random impulses and markovian switching under Non-Lipschitz conditions*, J. Acta Math. Sin, *27(3)* (2011), 519–536.
- [18] X. Zhao, *Mean square Hyers-Ulam stability of stochastic differential equations driven by Brownian motion*, Adv. Difference. Equ, *2016(1)* (2016), 1–12.
- [19] Y. Zhou and S. Wu, *Existence and uniqueness of solutions to stochastic differential equations with random impulses under Lipschitz conditions*, Chinese J. Appl. Proba. Statist, *26(4)* (2010), 347–356.

